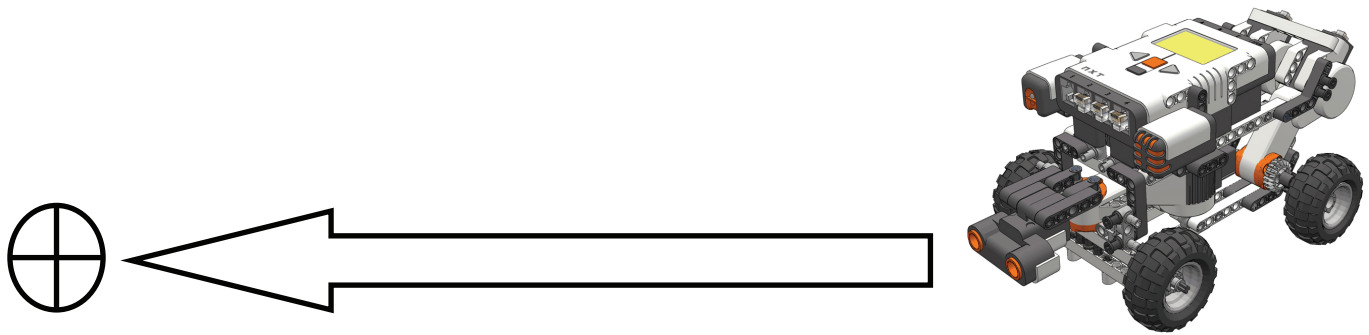
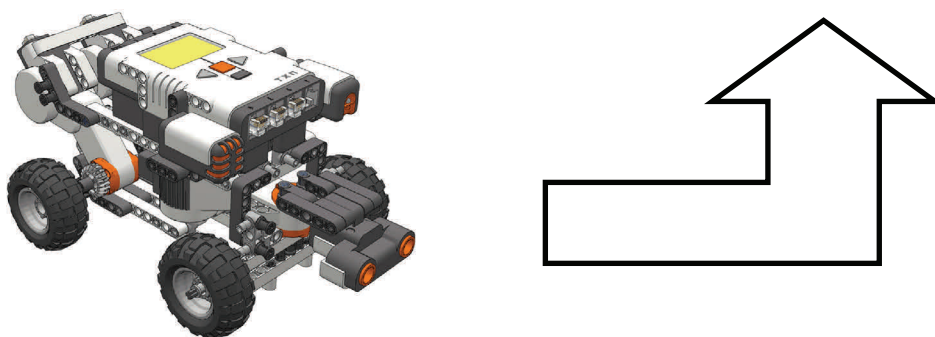


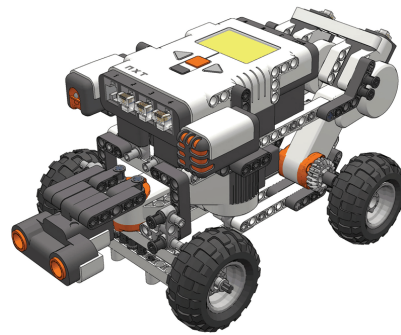
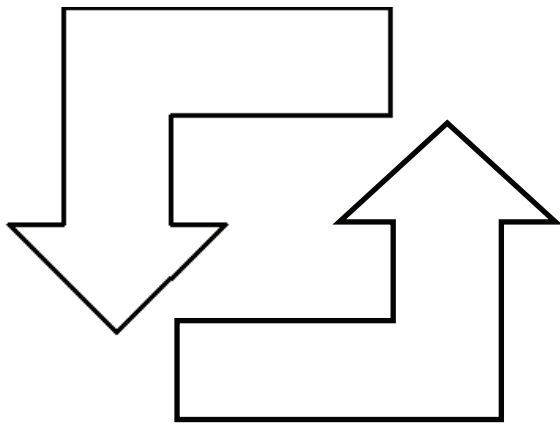
**Make the robot move forward
to a designated spot.**



**Make the robot move forward
and then turn.**



Program the robot to move in a perfect square.



Create an arm attachment to pick up an object.



Use the touch sensor



Use the light sensor

